

CE SAR TEST REPORT

Equipment : Sterling-LWB5+ WiFi 5 + Bluetooth 5.2 USB Adapter
Brand Name : Laird Connectivity
Model Name : Sterling LWB5+
Applicant : Laird Connectivity, LLC.
Manufacturer : W66N220 Commerce Court, Cedarburg, Wisconsin 53012, USA
Standard : EN 50566:2017
EN IEC 62311:2020
EN 62209-2:2010
EN 62479:2010
EN 50663:2017
EN 50665:2017

The product was received on Jul. 10, 2021 and testing was started from Aug. 01, 2021 and completed on Aug. 01, 2021. We, SPORTON INTERNATIONAL INC., would like to declare that the tested sample provide by manufacturer and the test data has been evaluated in accordance with the test procedures given in above list standard and has been pass the requirement.

The test results in this report apply exclusively to the tested model / sample. Without written approval of SPORTON INTERNATIONAL INC. EMC & Wireless Communications Laboratory, the test report shall not be reproduced except in full.



Approved by: Cona Huang / Deputy Manager



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History of this test report

Report No.	Version	Description	Issued Date
EA160207	Rev. 01	Initial issue of report	Aug. 19, 2021

1. Statement of Compliance

The maximum results of Specific Absorption Rate (SAR) found during testing for **Laird Connectivity, LLC., Sterling-LWB5+ WiFi 5 + Bluetooth 5.2 USB Adapter, Sterling LWB5+**, are as follows.

Frequency Band		Highest SAR Summary
		Body (Separation 5mm)
		10g SAR (W/kg)
WLAN	2.4GHz WLAN	0.267
	5GHz WLAN	0.465
Date of Testing:		2021/8/1

This device is compliance with Specific Absorption Rate (SAR) for general population/uncontrolled exposure (Localized 10-gram SAR for trunk, limit: 2.0W/kg) specified in Council Recommendation 1999/519/EC, and ICNIRP Guidelines, and RED (Directive 2014/53/EU), and had been tested in accordance with the measurement methods and procedures specified in EN50566:2017, EN IEC 62311:2020, EN 50665:2017, EN 62479:2010, EN 50663:2017 and EN 62209-2:2010.

Reviewed by: Jason Wang
Report Producer: Daisy Peng

2. Guidance Applied

The Specific Absorption Rate (SAR) testing specification, method, and procedure for this device is in accordance with the following standards:

- Council Recommendation 1999/519/EC
- EN IEC 62311: 2020
- EN 50566:2017
- EN 62209-2:2010
- EN 62479:2010
- EN 50663:2017
- EN 50665:2017

3. Equipment Under Test (EUT)

3.1 General Information

Product Feature & Specification	
Equipment Name	Sterling-LWB5+ WiFi 5 + Bluetooth 5.2 USB Adapter
Brand Name	Laird Connectivity
Model Name	Sterling LWB5+
Wireless Technology and Frequency Range	WLAN 2.4GHz Band: 2400 MHz ~ 2483.5 MHz WLAN 5GHz Band: 5150 MHz ~ 5350 MHz, 5470 MHz ~ 5725 MHz, 5725 MHz ~ 5850 MHz Bluetooth: 2400 MHz ~ 2483.5 MHz
Mode	WLAN: 802.11a/b/g/n/ac HT20/HT40/VHT20/VHT40/VHT80 Bluetooth BR/EDR/LE
HW Version	R4.0
EUT Stage	Identical Prototype

4. Basic Restrictions

Depending on frequency, the following physical quantities (dosimetric/exposimetric quantities) are used to specify the basic restrictions on electromagnetic fields:

- between 0 and 1 Hz basic restrictions are provided for magnetic flux density for static magnetic fields (0 Hz) and current density for time-varying fields up to 1 Hz, in order to prevent effects on the cardiovascular and central nervous system.
- Between 1 Hz and 10 MHz basic restrictions are provided for current density to prevent effects on nervous system functions.
- Between 100 kHz and 10 GHz basic restrictions on SAR are provided to prevent whole-body heat stress and excessive localized heating of tissues. In the range 100 kHz to 10 MHz, restrictions on both current density and SAR are provided.
- Between 10 GHz and 300 GHz basic restrictions on power density are provided to prevent heating in tissue at or near the body surface.

The basic restrictions, given in Table 1, are set so as to account for uncertainties related to individual sensitivities, environmental conditions, and for the fact that the age and health status of members of the public vary.

Table 1

Basic restrictions for electric, magnetic and electromagnetic fields
(0 Hz to 300 GHz)

Frequency range	Magnetic flux density (mT)	Current density (mA/m ²) (rms)	Whole body average SAR (W/kg)	Localised SAR (head and trunk) (W/kg)	Localised SAR (limbs) (W/kg)	Power density, S (W/m ²)
0 Hz	40	—	—	—	—	—
>0-1 Hz	—	8	—	—	—	—
1-4 Hz	—	8/f	—	—	—	—
4-1 000 Hz	—	2	—	—	—	—
1 000 Hz-100 kHz	—	f/500	—	—	—	—
100 kHz-10 MHz	—	f/500	0,08	2	4	—
10 MHz-10 GHz	—	—	0,08	2	4	—
10-300 GHz	—	—	—	—	—	10

5. Specific Absorption Rate (SAR)

5.1 Introduction

SAR is related to the rate at which energy is absorbed per unit mass in an object exposed to a radio field. The SAR distribution in a biological body is complicated and is usually carried out by experimental techniques or numerical modeling. The standard recommends limits for two tiers of groups, occupational/controlled and general population/uncontrolled, based on a person's awareness and ability to exercise control over his or her exposure. In general, occupational/controlled exposure limits are higher than the limits for general population/uncontrolled.

5.2 SAR Definition

The SAR definition is the time derivative (rate) of the incremental energy (dW) absorbed by (dissipated in) an incremental mass (dm) contained in a volume element (dv) of a given density (ρ). The equation description is as below:

$$SAR = \frac{d}{dt} \left(\frac{dW}{dm} \right) = \frac{d}{dt} \left(\frac{dW}{\rho dv} \right)$$

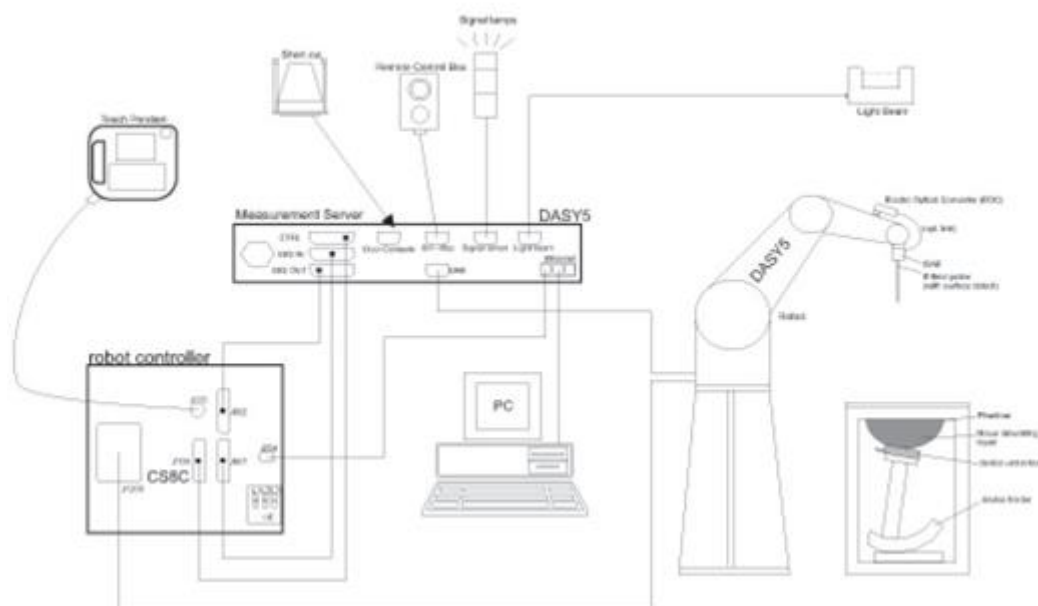
SAR is expressed in units of Watts per kilogram (W/kg)

$$SAR = \frac{\sigma |E|^2}{\rho}$$

Where: σ is the conductivity of the tissue, ρ is the mass density of the tissue and E is the RMS electrical field strength.

6. System Description and Setup

The DASY system used for performing compliance tests consists of the following items:



- A standard high precision 6-axis robot with controller, teach pendant and software. An arm extension for accommodating the data acquisition electronics (DAE).
- An isotropic Field probe optimized and calibrated for the targeted measurement.
- A data acquisition electronics (DAE) which performs the signal amplification, signal multiplexing, AD-conversion, offset measurements, mechanical surface detection, collision detection, etc. The unit is battery powered with standard or rechargeable batteries. The signal is optically transmitted to the EOC.
- The Electro-optical converter (EOC) performs the conversion from optical to electrical signals for the digital communication to the DAE. To use optical surface detection, a special version of the EOC is required. The EOC signal is transmitted to the measurement server.
- The function of the measurement server is to perform the time critical tasks such as signal filtering, control of the robot operation and fast movement interrupts.
- The Light Beam used is for probe alignment. This improves the (absolute) accuracy of the probe positioning.
- A computer running WinXP or Win7 and the DASY software.
- Remote control and teach pendant as well as additional circuitry for robot safety such as warning lamps, etc.
- The phantom, the device holder and other accessories according to the targeted measurement.

6.1 Test Site Location


The SAR measurement facilities used to collect data are within both Sporton Lab list below test site location are accredited to ISO 17025 by Taiwan Accreditation Foundation (TAF code: 1190 and 3786).

Test Site	EMC & Wireless Communications Laboratory		Wensan Laboratory		
Test Site Location	TW1190 No.52, Huaya 1st Rd., Guishan Dist., Taoyuan City 333, Taiwan		TW3786 No.58, Aly. 75, Ln. 564, Wenhua 3rd, Rd., Guishan Dist., Taoyuan City 333010, Taiwan		
Test Site No.	SAR01-HY	SAR03-HY	SAR08-HY	SAR09-HY	SAR15-HY
	SAR04-HY	SAR05-HY	SAR11-HY	SAR12-HY	
	SAR06-HY	SAR10-HY	SAR13-HY	SAR14-HY	


6.2 E-Field Probe

The SAR measurement is conducted with the dosimetric probe (manufactured by SPEAG). The probe is specially designed and calibrated for use in liquid with high permittivity. The dosimetric probe has special calibration in liquid at different frequency. This probe has a built in optical surface detection system to prevent from collision with phantom.

<ES3DV3 Probe>

Construction	Symmetric design with triangular core Interleaved sensors Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	
Frequency	10 MHz – 4 GHz; Linearity: ± 0.2 dB (30 MHz – 4 GHz)	
Directivity	± 0.2 dB in TSL (rotation around probe axis) ± 0.3 dB in TSL (rotation normal to probe axis)	
Dynamic Range	5 μ W/g – >100 mW/g; Linearity: ± 0.2 dB	
Dimensions	Overall length: 337 mm (tip: 20 mm) Tip diameter: 3.9 mm (body: 12 mm) Distance from probe tip to dipole centers: 3.0 mm	

<EX3DV4 Probe>

Construction	Symmetric design with triangular core Built-in shielding against static charges PEEK enclosure material (resistant to organic solvents, e.g., DGBE)	
Frequency	10 MHz – >6 GHz Linearity: ± 0.2 dB (30 MHz – 6 GHz)	
Directivity	± 0.3 dB in TSL (rotation around probe axis) ± 0.5 dB in TSL (rotation normal to probe axis)	
Dynamic Range	10 μ W/g – >100 mW/g Linearity: ± 0.2 dB (noise: typically <1 μ W/g)	
Dimensions	Overall length: 337 mm (tip: 20 mm) Tip diameter: 2.5 mm (body: 12 mm) Typical distance from probe tip to dipole centers: 1 mm	

6.3 Data Acquisition Electronics (DAE)

The data acquisition electronics (DAE) consists of a highly sensitive electrometer-grade preamplifier with auto-zeroing, a channel and gain-switching multiplexer, a fast 16 bit AD-converter and a command decoder and control logic unit. Transmission to the measurement server is accomplished through an optical downlink for data and status information as well as an optical uplink for commands and the clock.


The input impedance of the DAE is 200 MOhm; the inputs are symmetrical and floating. Common mode rejection is above 80 dB.



Fig 5.1 Photo of DAE


6.4 Phantom

<SAM Twin Phantom>

Shell Thickness	2 ± 0.2 mm; Center ear point: 6 ± 0.2 mm	
Filling Volume	Approx. 25 liters	
Dimensions	Length: 1000 mm; Width: 500 mm; Height: adjustable feet	
Measurement Areas	Left Hand, Right Hand, Flat Phantom	

The bottom plate contains three pair of bolts for locking the device holder. The device holder positions are adjusted to the standard measurement positions in the three sections. A white cover is provided to tap the phantom during off-periods to prevent water evaporation and changes in the liquid parameters. On the phantom top, three reference markers are provided to identify the phantom position with respect to the robot.

<ELI Phantom>

Shell Thickness	2 ± 0.2 mm (sagging: <1%)	
Filling Volume	Approx. 30 liters	
Dimensions	Major ellipse axis: 600 mm Minor axis: 400 mm	

The ELI phantom is intended for compliance testing of handheld and body-mounted wireless devices in the frequency range of 30 MHz to 6 GHz. ELI4 is fully compatible with standard and all known tissue simulating liquids.

6.5 Device Holder

<Mounting Device for Hand-Held Transmitter>

In combination with the Twin SAM V5.0/V5.0c or ELI phantoms, the Mounting Device for Hand-Held Transmitters enables rotation of the mounted transmitter device to specified spherical coordinates. At the heads, the rotation axis is at the ear opening. Transmitter devices can be easily and accurately positioned according to IEC 62209-1, IEEE 1528, FCC, or other specifications. The device holder can be locked for positioning at different phantom sections (left head, right head, flat). And upgrade kit to Mounting Device to enable easy mounting of wider devices like big smart-phones, e-books, small tablets, etc. It holds devices with width up to 140 mm.



Mounting Device for Hand-Held Transmitters



Mounting Device Adaptor for Wide-Phones

<Mounting Device for Laptops and other Body-Worn Transmitters>

The extension is lightweight and made of POM, acrylic glass and foam. It fits easily on the upper part of the mounting device in place of the phone positioned. The extension is fully compatible with the SAM Twin and ELI phantoms.



Mounting Device for Laptops

7. Measurement Procedures

The measurement procedures are as follows:

- (a) Use base station simulator (if applicable) or engineering software to transmit RF power continuously (continuous Tx) in the middle channel.
- (b) Keep EUT to radiate maximum output power or 100% duty factor (if applicable)
- (c) Measure output power through RF cable and power meter.
- (d) Place the EUT in the positions as setup photos demonstrates.
- (e) Set scan area, grid size and other setting on the DASY software.
- (f) Measure SAR transmitting at the middle channel for all applicable exposure positions.
- (g) Identify the exposure position and device configuration resulting the highest SAR
- (h) Measure SAR at the lowest and highest channels at the worst exposure position and device configuration.

According to the test standard, the recommended procedure for assessing the peak spatial-average SAR value consists of the following steps:

- (a) Power reference measurement
- (b) Area scan
- (c) Zoom scan
- (d) Power drift measurement

7.1 Spatial Peak SAR Evaluation

The procedure for spatial peak SAR evaluation has been implemented according to the test standard. It can be conducted for 1g and 10g, as well as for user-specific masses. The DASY software includes all numerical procedures necessary to evaluate the spatial peak SAR value.

The base for the evaluation is a "cube" measurement. The measured volume must include the 1g and 10g cubes with the highest averaged SAR values. For that purpose, the center of the measured volume is aligned to the interpolated peak SAR value of a previously performed area scan.

The entire evaluation of the spatial peak values is performed within the post-processing engine (SEMCAD). The system always gives the maximum values for the 1g and 10g cubes. The algorithm to find the cube with highest averaged SAR is divided into the following stages:

- (a) Extraction of the measured data (grid and values) from the Zoom Scan
- (b) Calculation of the SAR value at every measurement point based on all stored data (A/D values and measurement parameters)
- (c) Generation of a high-resolution mesh within the measured volume
- (d) Interpolation of all measured values from the measurement grid to the high-resolution grid
- (e) Extrapolation of the entire 3-D field distribution to the phantom surface over the distance from sensor to surface
- (f) Calculation of the averaged SAR within masses of 1g and 10g

7.2 Power Reference Measurement

The Power Reference Measurement and Power Drift Measurements are for monitoring the power drift of the device under test in the batch process. The minimum distance of probe sensors to surface determines the closest measurement point to phantom surface. This distance cannot be smaller than the distance of sensor calibration points to probe tip as defined in the probe properties.

7.3 Area & Zoom Scan Procedures

- a) Measure the local SAR at a test point within 8 mm of the phantom inner surface that is closest to the DUT.
- b) Measure the two-dimensional SAR distribution within the phantom (area scan procedure). The boundary of the measurement area shall not be closer than 20 mm from the phantom side walls. The distance between the measurement points should enable the detection of the location of local maximum with an accuracy of better than half the linear dimension of the tissue cube after interpolation. A maximum grid spacing of 20 mm for frequencies below 3 GHz and $(60/f \text{ [GHz]})$ mm for frequencies of 3 GHz and greater is recommended. The maximum distance between the geometrical center of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\ln(2)/2$ mm for frequencies of 3 GHz and greater, where \ln is the plane wave skin depth and $\ln(x)$ is the natural logarithm. The maximum variation of the sensor-phantom surface distance shall be 1 mm for frequencies below 3 GHz and 0,5 mm for frequencies of 3 GHz and greater. At all measurement points the angle of the probe with respect to the line normal to the surface should be less than 5°. If this cannot be achieved for a measurement distance to the phantom inner surface shorter than the probe diameter, additional uncertainty evaluation is needed.
- c) From the scanned SAR distribution, identify the position of the maximum SAR value, in addition identify the positions of any local maxima with SAR values within 2 dB of the maximum value that will not be within the zoom scan of other peaks; additional peaks shall be measured only when the primary peak is within 2 dB of the SAR compliance limit (e.g., 1 W/kg for 1,6 W/kg 1 g limit, or 1,26 W/kg for 2 W/kg, 10 g limit).
- d) Measure the three-dimensional SAR distribution at the local maxima locations identified in step c) (zoom scan procedure). The horizontal grid step shall be $(24 / f \text{ [GHz]})$ mm or less but not more than 8 mm. The minimum zoom scan size is 30 mm by 30 mm by 30 mm for frequencies below 3 GHz. For higher frequencies, the minimum zoom scan size can be reduced to 22 mm by 22 mm by 22 mm. The grid step in the vertical direction shall be $(8 \cdot f \text{ [GHz]})$ mm or less but not more than 5 mm, if uniform spacing is used (Annex C.3.3 of IEC 62209-1:2016). If variable spacing is used in the vertical direction, the maximum spacing between the two closest measured points to the phantom shell shall be $(12/f \text{ [GHz]})$ mm or less but not more than 4 mm, and the spacing between farther points shall increase by an incremental factor not exceeding 1,5. When variable spacing is used, extrapolation routines shall be tested with the same spacing as used in measurements. The maximum distance between the geometrical center of the probe detectors and the inner surface of the phantom shall be 5 mm for frequencies below 3 GHz and $\ln(2)/2$ mm for frequencies of 3 GHz and greater, where the plane wave skin depth and $\ln(x)$ is the natural logarithm. Separate grids shall be centered on each of the local SAR maxima found in step c). Uncertainties due to field distortion between the media boundary and the dielectric enclosure of the probe should also be minimized, which is achieved if the distance between the phantom surface and physical tip of the probe is larger than probe tip diameter. Other methods may utilize correction procedures for these boundary effects that enable high precision measurements closer than half the probe diameter. For all measurement points, the angle of the probe with respect to the flat phantom surface shall be less than 5°.

7.4 Volume Scan Procedures

The volume scan is used for assess overlapping SAR distributions for antennas transmitting in different frequency bands. It is equivalent to an oversized zoom scan used in standalone measurements. The measurement volume will be used to enclose all the simultaneous transmitting antennas. For antennas transmitting simultaneously in different frequency bands, the volume scan is measured separately in each frequency band. In order to sum correctly to compute the 1g or 10g aggregate SAR, the EUT remain in the same test position for all measurements and all volume scan use the same spatial resolution and grid spacing. When all volume scan were completed, the software, SEMCAD postprocessor can combine and subsequently superpose these measurement data to calculating the multiband SAR.

7.5 SAR Averaged Methods

In DASY, the interpolation and extrapolation are both based on the modified Quadratic Shepard's method. The interpolation scheme combines a least-square fitted function method and a weighted average method which are the two basic types of computational interpolation and approximation.

Extrapolation routines are used to obtain SAR values between the lowest measurement points and the inner phantom surface. The extrapolation distance is determined by the surface detection distance and the probe sensor offset. The uncertainty increases with the extrapolation distance. To keep the uncertainty within 1% for the 1 g and 10 g cubes, the extrapolation distance should not be larger than 5 mm.

7.6 Power Drift Monitoring

All SAR testing is under the EUT install full charged battery and transmit maximum output power. In DASY measurement software, the power reference measurement and power drift measurement procedures are used for monitoring the power drift of EUT during SAR test. Both these procedures measure the field at a specified reference position before and after the SAR testing. The software will calculate the field difference in dB. If the power drifts more than 5%, the SAR will be retested.

8. Test Equipment List

Manufacturer	Name of Equipment	Type/Model	Serial Number	Calibration	
				Last Cal.	Due Date
SPEAG	2450MHz System Validation Kit ⁽²⁾	D2450V2	929	Nov. 21, 2019	Nov. 19, 2021
SPEAG	5GHz System Validation Kit	D5GHzV2	1006	Sep. 27, 2018	Sep. 24, 2021
SPEAG	Data Acquisition Electronics	DAE4	1311	Aug. 25, 2020	Aug. 24, 2021
SPEAG	Dosimetric E-Field Probe	EX3DV4	3898	Jun. 24, 2021	Jun. 23, 2022
RCPTWN	Thermometer	HTC-1	TM560-2	Nov. 10, 2020	Nov. 09, 2021
SPEAG	Device Holder	N/A	N/A	N/A	N/A
Anritsu	Signal Generator	MG3710A	6201502524	Nov. 11, 2020	Nov. 10, 2021
Keysight	ENA Network Analyzer	E5071C	MY46104758	Sep. 03, 2020	Sep. 02, 2021
SPEAG	Dielectric Probe Kit	DAK-3.5	1126	Sep. 16, 2020	Sep. 15, 2021
LINE SEIKI	Digital Thermometer	DTM3000-spezial	2942	Nov. 06, 2020	Nov. 05, 2021
Anritsu	Power Meter	ML2495A	1419002	Aug. 19, 2020	Aug. 18, 2021
Anritsu	Power Sensor	MA2411B	1911176	Aug. 18, 2020	Aug. 17, 2021
Anritsu	Power Meter	ML2495A	1804003	Oct. 21, 2020	Oct. 20, 2021
Anritsu	Power Sensor	MA2411B	1726150	Oct. 21, 2020	Oct. 20, 2021
Agilent	Spectrum Analyzer	E4408B	MY44211028	Aug. 27, 2020	Aug. 26, 2021
Anritsu	Spectrum Analyzer	N9010A	MY53470118	Jan. 15, 2021	Jan. 14, 2022
Mini-Circuits	Power Amplifier	ZVE-8G+	6418	Oct. 21, 2020	Oct. 20, 2021
Mini-Circuits	Power Amplifier	ZVE-8G+	479102029	Aug. 26, 2020	Aug. 25, 2021
ATM	Dual Directional Coupler	C122H-10	P610410z-02	Note 1	
Woken	Attenuator 1	WK0602-XX	N/A	Note 1	
PE	Attenuator 2	PE7005-10	N/A	Note 1	
PE	Attenuator 3	PE7005-3	N/A	Note 1	

General Note:

1. Prior to system verification and validation, the path loss from the signal generator to the system check source and the power meter, which includes the amplifier, cable, attenuator and directional coupler, was measured by the network analyzer. The reading of the power meter was offset by the path loss difference between the path to the power meter and the path to the system check source to monitor the actual power level fed to the system check source.
2. The dipole calibration interval can be extended to 3 years with justification according to KDB 865664 D01. The dipoles are also not physically damaged, or repaired during the interval. The justification data in appendix C can be found which the return loss is < -20dB, within 20% of prior calibration, the impedance is within 5 ohm of prior calibration for each dipole.

9. System Verification

9.1 Tissue Verification

The tissue dielectric parameters of tissue-equivalent media used for SAR measurements must be characterized within a temperature range of 18°C to 25°C, measured with calibrated instruments and apparatuses, such as network analyzers and temperature probes. The temperature of the tissue-equivalent medium during SAR measurement must also be within 18°C to 25°C and within $\pm 2^\circ\text{C}$ of the temperature when the tissue parameters are characterized. The tissue dielectric measurement system must be calibrated before use. The dielectric parameters must be measured before the tissue-equivalent medium is used in a series of SAR measurements.

The liquid tissue depth was at least 15cm in the phantom for all SAR testing

<Tissue Dielectric Parameter Check Results>

Frequency (MHz)	Liquid Temp. (°C)	Conductivity (σ)	Permittivity (ϵ_r)	Conductivity Target (σ)	Permittivity Target (ϵ_r)	Delta (σ) (%)	Delta (ϵ_r) (%)	Limit (%)	Date
2450	22.5	1.779	38.563	1.80	39.20	-1.17	-1.63	± 5	2021/8/1
5250	22.5	4.643	35.784	4.71	35.95	-1.42	-0.46	± 5	2021/8/1
5600	22.5	4.970	35.326	5.07	35.50	-1.97	-0.49	± 5	2021/8/1

9.2 System Performance Check Results

Comparing to the original SAR value provided by SPEAG, the verification data should be within its specification of 10 %. Below table shows the target SAR and measured SAR after normalized to 1W input power. The table below indicates the system performance check can meet the variation criterion and the plots can be referred to Appendix A of this report.

Test Site	Date	Frequency (MHz)	Input Power (mW)	Dipole S/N	Probe S/N	DAE S/N	Measured 10g SAR (W/kg)	Targeted 10g SAR (W/kg)	Normalized 10g SAR (W/kg)	Deviation (%)
SAR05-HY	2021/8/1	2450	50	D2450V2-929	EX3DV4 - SN3898	DAE4 Sn1311	1.21	24.70	24.2	-2.02
SAR05-HY	2021/8/1	5250	100	D5GHzV2-1006-5250	EX3DV4 - SN3898	DAE4 Sn1311	2.24	23.20	22.4	-3.45
SAR05-HY	2021/8/1	5600	100	D5GHzV2-1006-5600	EX3DV4 - SN3898	DAE4 Sn1311	2.23	23.80	22.3	-6.30

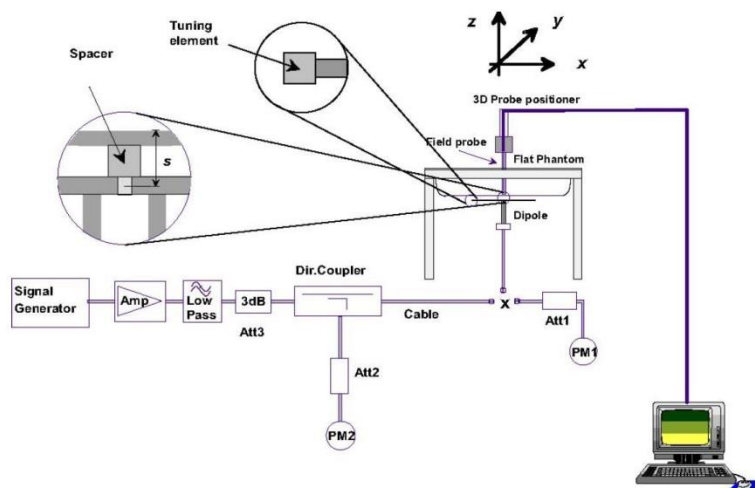






Fig 10.2.1 System Performance Check Setup



Fig 10.2.2 Setup Photo

10. RF Exposure Positions

This EUT was tested in four different USB configurations. They are “direct laptop plug-in for configuration 1 and 4”, “USB cable plug-in for configuration 2 and 3”, and “direct laptop plug-in for Tip Mode (the tip of the EUT)” shown as below. Both direct laptop plug-in and USB cable plug-in test configurations are tested with 5 mm separation between the particular dongle orientation and the flat phantom.

			
Configuration 1 (Horizontal Up)	Configuration 2 (Horizontal Down)	Configuration 3 (Vertical Front)	Configuration 4 (Vertical Back)

11. WLAN/BT Output Power (Unit: dBm)

<Bluetooth Conducted Power>

Mode	Channel	Frequency (MHz)	Average power (dBm)		
			1Mbps	2Mbps	3Mbps
BR /EDR	CH 00	2402	7.01	6.51	6.53
	CH 39	2441	6.69	5.51	5.53
	CH 78	2480	5.94	4.22	4.25
Tune-up Limit			7.50	7.00	7.00

Mode	Channel	Frequency (MHz)	Average power (dBm)	
			1Mbps	
LE	CH 00	2402	6.46	
	CH 19	2440	6.38	
	CH 39	2480	5.97	
Tune-up Limit			6.50	

General Note: Bluetooth Max output power is 7.50dBm is smaller than 20mw. According to EN 62479 and EN 50663, low power exclusion is applicable and Bluetooth operation complies with EMF basic restriction.

<WLAN Conducted Power>
General Note:

1. For 2.4GHz SAR testing was chosen the mode with highest output power, which is 802.11g 6Mbps, at middle channel to test SAR and determine the worst configuration for further high/low channel testing.
2. For 5.2GHz SAR testing was chosen the mode with highest output power, which is 802.11ac-VHT20 MCS0, at middle channel to test SAR and determine the worst configuration for further high/low channel testing.
3. For 5.5GHz SAR testing was chosen the mode with highest output power, which is 802.11ac-VHT80 MCS0, at middle channel to test SAR and determine the worst configuration for further high/low channel testing.
4. The 5.8GHz WLAN max output power is 9dBm which is smaller than 20mW. According to EN 62479 and EN 50663, low power exclusion is applicable and 5.8GHz WLAN operation complies with RF basic restriction

	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Duty Cycle %
2.4GHz WLAN	802.11b 1Mbps	1	2412	15.41	15.50	99.75
		7	2442	15.34	15.50	
		13	2472	15.11	15.50	
	802.11g 6Mbps	1	2412	16.22	17.00	99.00
		7	2442	16.55	17.00	
		13	2472	16.30	17.00	
	802.11n-HT20 MCS0	1	2412	16.54	17.00	98.90
		7	2442	16.45	17.00	
		13	2472	16.32	17.00	
	802.11n-HT40 MCS0	3	2422	16.32	17.00	97.80
		7	2442	16.28	17.00	
		11	2462	16.24	17.00	

	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Duty Cycle %
5.2GHz WLAN	802.11a 6Mbps	36	5180	17.58	18.00	97.85
		52	5260	17.55	18.00	
		64	5320	17.54	18.00	
	802.11n-HT20 MCS0 802.11ac-VHT20 MCS0	36	5180	17.60	18.00	97.65
		52	5260	17.53	18.00	
		64	5320	17.54	18.00	
	802.11n-HT40 MCS0 802.11ac-VHT40 MCS0	38	5190	15.48	15.50	94.20
		54	5270	16.20	16.50	
		62	5310	16.28	16.50	
	802.11ac-VHT80 MCS0	42	5210	16.33	16.50	88.50
		58	5290	15.55	16.00	

5.5GHz WLAN	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Duty Cycle %
	802.11a 6Mbps	100	5500	16.46	16.50	97.88
		116	5580	16.32	16.50	
		140	5700	17.75	18.00	
	802.11n-HT20 MCS0 802.11ac-VHT20 MCS0	100	5500	16.52	17.00	97.71
		116	5580	16.05	16.50	
		140	5700	15.75	16.00	
	802.11n-HT40 MCS0 802.11ac-VHT40 MCS0	102	5510	13.25	13.50	94.50
		110	5550	15.58	16.00	
		134	5670	16.83	17.00	
	802.11ac-VHT80 MCS0	106	5530	16.39	16.50	88.60
		122	5610	17.92	18.00	

5.8GHz WLAN	Mode	Channel	Frequency (MHz)	Average power (dBm)	Tune-Up Limit	Duty Cycle %
	802.11a 6Mbps	149	5745	8.95	9.00	97.90
		157	5785	8.95	9.00	
		165	5825	8.68	9.00	
	802.11n-HT20 MCS0 802.11ac-VHT20 MCS0	149	5745	8.92	9.00	97.70
		157	5785	8.82	9.00	
		165	5825	8.60	9.00	
	802.11n-HT40 MCS0 802.11ac-VHT40 MCS0	151	5755	8.71	9.00	94.90
		159	5795	8.67	9.00	
	802.11ac-VHT80 MCS0	155	5775	8.96	9.00	88.60

12. Antenna Location



Front View

13. SAR Test Results

General Note:

1. The reported SAR is the measured SAR value adjusted for maximum tune-up tolerance.
 - a. Tune-up scaling Factor = tune-up limit power (mW) / EUT RF power (mW), where tune-up limit is the maximum rated power among all production units.
 - b. For SAR testing of WLAN signal with non-100% duty cycle, the measured SAR is scaled-up by the duty cycle scaling factor which is equal to "1/(duty cycle)"
 - c. For WLAN: Reported SAR(W/kg)= Measured SAR(W/kg)* Duty Cycle scaling factor * Tune-up scaling factor
2. When the WLAN transmission was verified using a spectrum analyzer.
3. WLAN and Bluetooth share the same antenna, and cannot transmit simultaneously.

13.1 Body SAR

<WLAN SAR>

Plot No.	Band	Mode	Test Position	Gap (mm)	Ch.	Freq. (MHz)	Average Power (dBm)	Tune-Up Limit (dBm)	Tune-up Scaling Factor	Duty Cycle %	Duty Cycle Scaling Factor	Power Drift (dB)	Measured 10g SAR (W/kg)	Reported 10g SAR (W/kg)
	WLAN2.4GHz	802.11g 6Mbps	Horizontal Up	5mm	7	2442	16.55	17.00	1.109	99.00	1.010	-0.12	0.220	0.246
	WLAN2.4GHz	802.11g 6Mbps	Horizontal Down	5mm	7	2442	16.55	17.00	1.109	99.00	1.010	-0.18	0.215	0.241
	WLAN2.4GHz	802.11g 6Mbps	Vertical Front	5mm	7	2442	16.55	17.00	1.109	99.00	1.010	-0.19	0.071	0.080
	WLAN2.4GHz	802.11g 6Mbps	Vertical Back	5mm	7	2442	16.55	17.00	1.109	99.00	1.010	0.03	0.136	0.152
	WLAN2.4GHz	802.11g 6Mbps	Tip Mode	5mm	7	2442	16.55	17.00	1.109	99.00	1.010	0.09	0.039	0.044
	WLAN2.4GHz	802.11g 6Mbps	Horizontal Up	5mm	1	2412	16.22	17.00	1.197	99.00	1.010	0.16	0.127	0.154
01	WLAN2.4GHz	802.11g 6Mbps	Horizontal Up	5mm	13	2472	16.30	17.00	1.175	99.00	1.010	-0.18	0.225	0.267
	WLAN5GHz	802.11ac-VHT20 MCS0	Horizontal Up	5mm	52	5260	17.53	18.00	1.114	97.65	1.024	0.14	0.212	0.242
	WLAN5GHz	802.11ac-VHT20 MCS0	Horizontal Down	5mm	52	5260	17.53	18.00	1.114	97.65	1.024	0.13	0.170	0.194
	WLAN5GHz	802.11ac-VHT20 MCS0	Vertical Front	5mm	52	5260	17.53	18.00	1.114	97.65	1.024	-0.07	0.168	0.192
	WLAN5GHz	802.11ac-VHT20 MCS0	Vertical Back	5mm	52	5260	17.53	18.00	1.114	97.65	1.024	0.02	0.126	0.144
	WLAN5GHz	802.11ac-VHT20 MCS0	Tip Mode	5mm	52	5260	17.53	18.00	1.114	97.65	1.024	-0.15	0.183	0.209
	WLAN5GHz	802.11ac-VHT20 MCS0	Horizontal Up	5mm	36	5180	17.60	18.00	1.096	97.65	1.024	0.14	0.160	0.180
	WLAN5GHz	802.11ac-VHT20 MCS0	Horizontal Up	5mm	64	5320	17.54	18.00	1.112	97.65	1.024	0.19	0.300	0.342
02	WLAN5GHz	802.11ac-VHT80 MCS0	Horizontal Up	5mm	122	5610	17.92	18.00	1.019	88.60	1.129	0.05	0.404	0.465
	WLAN5GHz	802.11ac-VHT80 MCS0	Horizontal Down	5mm	122	5610	17.92	18.00	1.019	88.60	1.129	-0.04	0.329	0.378
	WLAN5GHz	802.11ac-VHT80 MCS0	Vertical Front	5mm	122	5610	17.92	18.00	1.019	88.60	1.129	-0.15	0.324	0.373
	WLAN5GHz	802.11ac-VHT80 MCS0	Vertical Back	5mm	122	5610	17.92	18.00	1.019	88.60	1.129	-0.07	0.240	0.276
	WLAN5GHz	802.11ac-VHT80 MCS0	Tip Mode	5mm	122	5610	17.92	18.00	1.019	88.60	1.129	-0.1	0.366	0.421
	WLAN5GHz	802.11ac-VHT80 MCS0	Horizontal Up	5mm	106	5530	16.39	16.50	1.026	88.60	1.129	0.16	0.291	0.337

Test Engineer : Bevis Chang

14. Uncertainty Assessment

The component of uncertainty may generally be categorized according to the methods used to evaluate them. The evaluation of uncertainty by the statistical analysis of a series of observations is termed a Type A evaluation of uncertainty. The evaluation of uncertainty by means other than the statistical analysis of a series of observation is termed a Type B evaluation of uncertainty. Each component of uncertainty, however evaluated, is represented by an estimated standard deviation, termed standard uncertainty, which is determined by the positive square root of the estimated variance.

A Type A evaluation of standard uncertainty may be based on any valid statistical method for treating data. This includes calculating the standard deviation of the mean of a series of independent observations; using the method of least squares to fit a curve to the data in order to estimate the parameter of the curve and their standard deviations; or carrying out an analysis of variance in order to identify and quantify random effects in certain kinds of measurement.

A type B evaluation of standard uncertainty is typically based on scientific judgment using all of the relevant information available. These may include previous measurement data, experience, and knowledge of the behavior and properties of relevant materials and instruments, manufacture's specification, data provided in calibration reports and uncertainties assigned to reference data taken from handbooks. Broadly speaking, the uncertainty is either obtained from an outdoor source or obtained from an assumed distribution, such as the normal distribution, rectangular or triangular distributions indicated in Table below

Uncertainty Distributions	Normal	Rectangular	Triangular	U-Shape
Multi-plying Factor ^(a)	1/ κ ^(b)	1/ $\sqrt{3}$	1/ $\sqrt{6}$	1/ $\sqrt{2}$

(a) standard uncertainty is determined as the product of the multiplying factor and the estimated range of variations in the measured quantity

(b) κ is the coverage factor

Standard Uncertainty for Assumed Distribution

The combined standard uncertainty of the measurement result represents the estimated standard deviation of the result. It is obtained by combining the individual standard uncertainties of both Type A and Type B evaluation using the usual "root-sum-squares" (RSS) methods of combining standard deviations by taking the positive square root of the estimated variances.

Expanded uncertainty is a measure of uncertainty that defines an interval about the measurement result within which the measured value is confidently believed to lie. It is obtained by multiplying the combined standard uncertainty by a coverage factor. Typically, the coverage factor ranges from 2 to 3. Using a coverage factor allows the true value of a measured quantity to be specified with a defined probability within the specified uncertainty range. For purpose of this document, a coverage factor two is used, which corresponds to confidence interval of about 95 %. The DASY uncertainty Budget is shown in the following tables.

The judgment of conformity in the report is based on the measurement results excluding the measurement uncertainty.

Error Description	Uncertainty Value (±%)	Probability	Divisor	(Ci) 1g	(Ci) 10g	Standard Uncertainty (1g) (±%)	Standard Uncertainty (10g) (±%)
Measurement System							
Probe Calibration	6.55	N	1	1	1	6.6	6.6
Axial Isotropy	4.70	R	1.732	0.7	0.7	1.9	1.9
Hemispherical Isotropy	9.60	R	1.732	0.7	0.7	3.9	3.9
Linearity	4.70	R	1.732	1	1	2.7	2.7
Modulation Response	4.68	R	1.732	1	1	2.7	2.7
System Detection Limits	1.00	R	1.732	1	1	0.6	0.6
Boundary Effects	2.00	R	1.732	1	1	1.2	1.2
Readout Electronics	0.30	N	1	1	1	0.3	0.3
Response Time	0.00	R	1.732	1	1	0.0	0.0
Integration Time	2.60	R	1.732	1	1	1.5	1.5
RF Ambient Noise	3.00	R	1.732	1	1	1.7	1.7
RF Ambient Reflections	3.00	R	1.732	1	1	1.7	1.7
Probe Positioner	0.40	R	1.732	1	1	0.2	0.2
Probe Positioning	6.70	R	1.732	1	1	3.9	3.9
Post-processing	4.00	R	1.732	1	1	2.3	2.3
Test Sample Related							
Device Holder	3.60	N	1	1	1	3.6	3.6
Test sample Positioning	3.03	N	1	1	1	3.0	3.0
Power Scaling	0.00	R	1.732	1	1	0.0	0.0
Power Drift	5.00	R	1.732	1	1	2.9	2.9
Phantom and Setup							
Phantom Uncertainty	7.60	R	1.732	1	1	4.4	4.4
SAR correction	0.00	R	1.732	1	0.84	0.0	0.0
Liquid Conductivity Repeatability	0.03	N	1	0.78	0.71	0.0	0.0
Liquid Conductivity (target)	5.00	R	1.732	0.78	0.71	2.3	2.0
Liquid Conductivity (mea.)	2.50	R	1.732	0.78	0.71	1.1	1.0
Temp. unc. - Conductivity	3.68	R	1.732	0.78	0.71	1.7	1.5
Liquid Permittivity Repeatability	0.02	N	1	0.23	0.26	0.0	0.0
Liquid Permittivity (target)	5.00	R	1.732	0.23	0.26	0.7	0.8
Liquid Permittivity (mea.)	2.50	R	1.732	0.23	0.26	0.3	0.4
Temp. unc. - Permittivity	0.84	R	1.732	0.23	0.26	0.1	0.1
Combined Std. Uncertainty						12.9%	12.5%
Coverage Factor for 95 %						K=2	K=2
Expanded STD Uncertainty						25.8%	25.1%

Uncertainty Budget for frequency range 30 MHz to 6 GHz according to IEC/EN 62209

15. References

- [1] Council Recommendation 1999/519/EC of July 1999 on the limitation of exposure of the general public to electromagnetic fields (0 Hz to 300 GHz)
- [2] EN 50566:2017, "Product standard to demonstrate the compliance of wireless communication devices with the basic restrictions and exposure limit values related to human exposure to electromagnetic fields in the frequency range from 30 MHz to 6 GHz: hand-held and body mounted devices in close proximity to the human body".
- [3] EN IEC 62311:2020, "Assessment of electronic and electrical equipment related to human exposure restrictions for electromagnetic fields (0 Hz – 300 GHz)"
- [4] EN 50665:2017, "Generic standard for assessment of electronic and electrical equipment related to human exposure restrictions for electromagnetic fields (0 Hz - 300 GHz)"
- [5] EN 62209-2:2010, "Human exposure to radio frequency fields from hand-held and body-mounted wireless communication devices. Human models, instrumentation, and procedures. Procedure to determine the specific absorption rate (SAR) for wireless communication devices used in close proximity to the human body (frequency range of 30 MHz to 6 GHz)"
- [6] EN 62479:2010 "Assessment of the compliance of low power electronic and electrical equipment with the basic restrictions related to human exposure to electromagnetic fields (10 MHz to 300 GHz)".
- [7] EN 50663:2017 " Generic standard for assessment of low power electronic and electrical equipment related to human exposure restrictions for electromagnetic fields (0 Hz - 300 GHz)".
- [8] SPEAG DASY System Handbook